

Matrices

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Definition:-

A set of $(m \times n)$ numbers arranged in the form of an ordered set of 'm rows' and 'n columns' is called **$m \times n$ matrix**.

$$* A = [a_{ij}]_{m \times n}$$

Where a_{ij} represents the element at the intersection of i^{th} row and j^{th} column.

a_{11}	a_{12}	...	a_{1n}
a_{21}	a_{22}	...	a_{2n}
a_{31}	a_{32}	...	a_{3n}
...
a_{m1}	a_{m2}	...	a_{mn}

Type of matrices

1. **Square matrix** :- A matrix in which the number of rows is equal to the number of column.

Example :

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 5 \end{bmatrix}_{2 \times 2}$$

$$B = \begin{bmatrix} 1 & -1 & 2 \\ 3 & 5 & -7 \\ 4 & 0 & 0 \end{bmatrix}_{3 \times 3}$$

2. **Horizontal matrix** :- matrix in which number of columns are more than number of rows.

Example : $\begin{bmatrix} 2 & 5 & 7 \\ 1 & -1 & 0 \end{bmatrix}$

3. **Vertical matrix** :- matrix in which number of rows are more than number of columns.

Example : $\begin{bmatrix} 2 & 1 \\ 5 & -1 \\ 7 & 0 \end{bmatrix}$

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4. **Row matrix**:- A matrix having only one row is called a row matrix.

Example: $[1 \ -1 \ 0]$

5. **Column matrix**:- A matrix having only one column is called a column matrix.

Example $\begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix}$

6. **Diagonal matrix**:- A square matrix $A = [a_{ij}]_{n \times n}$ is called a diagonal matrix if $a_{ij} = 0$ for all $i \neq j$.

A diagonal matrix of order $n \times n$ having d_1, d_2, \dots, d_n as diagonal elements is denoted by $\text{diag}[d_1, d_2, \dots, d_n]$.

Example: $\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

7. **Scalar matrix**:- A diagonal matrix in which all the diagonal elements are equal.

Example: $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

8. **Identity or Unit matrix**: A diagonal matrix in which all diagonal elements are equal to one.

The Identity matrix of order n is denoted by I_n .

Example: $I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}_{2 \times 2}$ $I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}_{3 \times 3}$

9. **Null matrix**: A matrix whose all elements are zero is called a null matrix or a zero matrix.

Example: $A = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ $B = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

10. **Upper Triangular matrix**: A square matrix $A = [a_{ij}]$ is called an upper triangular matrix if $a_{ij} = 0$ for all $i > j$.

Example: $A = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 5 \\ 0 & 0 & 2 \end{bmatrix}$

11. **Lower triangular matrix**: A square matrix $A = [a_{ij}]$ is called a lower triangular matrix if $a_{ij} = 0$ for all $i < j$.

Example: $A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 0 & 0 \\ 3 & 0 & 0 \end{bmatrix}$

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Operations of matrices

1. Equality of matrices - Two matrices of same order are equal if their corresponding elements are equal.

Example:
$$\begin{bmatrix} 2x+4 & 3y-x \\ x+2 & x+z \end{bmatrix} = \begin{bmatrix} 0 & 5 \\ 3 & -1 \end{bmatrix}$$

Find the value of $x+y+z$.

- A) 0 B) 1 C) -2 D) -6

2. Addition of matrices

Addition of two matrices is possible only if they are of same order.

The resultant matrix is obtained by addition of corresponding elements of two given matrices.

$$\begin{aligned} A &= [a_{ij}] \quad B = [b_{ij}] \\ \text{if } C &= A + B \\ \Rightarrow [c_{ij}] &= [a_{ij}] + [b_{ij}] \end{aligned}$$

Example:

$$\text{if } A = \begin{bmatrix} 2 & -1 \\ 0 & 6 \end{bmatrix}_{2 \times 2}$$

$$B = \begin{bmatrix} 4 & 7 \\ 2 & -2 \end{bmatrix}_{2 \times 2}$$

Then: $A+B$

~~A+B~~

Properties of matrix addition

1. Matrix addition is commutative $A+B = B+A$
2. Matrix addition is associative $A+(B+C) = (A+B)+C$
3. Cancellation law holds i.e., if: $A+B = A+C$

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3. Subtraction of matrices .

Subtraction of two matrices is possible only if they are of same order .

The resultant matrix is obtained by subtraction of corresponding elements of two given matrices .

$$A = [a_{ij}] \quad , \quad B = [b_{ij}]$$

$$\text{if } C = A - B$$

$$\Rightarrow [c_{ij}] = [a_{ij}] - [b_{ij}]$$

4. Multiplication of matrix with a scalar .

The scalar gets multiplied in every element of the matrix .

Example : $A = \begin{bmatrix} 2 & 5 & 1 \\ 0 & 6 & -1 \end{bmatrix}_{2 \times 3}$

then,

$$2A = \begin{bmatrix} 4 & 10 & 2 \\ 0 & 12 & -2 \end{bmatrix}$$

5. Multiplication of two matrices

Matrix multiplication is done Row by column .

for the two matrices $A_{m \times n}$ and $B_{p \times q}$. the multiplication $(A \times B)$ is possible only if number of columns of A is equal to the number of rows of B . i.e. " $n = p$ "

The resultant matrix C will be of the order $m \times q$

Example: $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$ and $B = \begin{bmatrix} 4 & 5 & 6 \\ 7 & 8 & 9 \\ 1 & 2 & 3 \end{bmatrix}$
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Find AB and BA .

Properties of matrix multiplication.

1. In general, $AB \neq BA$. i.e. commutative property does not hold. They may be equal for special set of matrices A and B .
2. Multiplication of matrices is distributive w.r.t. addition of matrices $A(B+C) = AB + AC$.
3. Matrix multiplication is associative if conformability is assured $A(BC) = (AB)C$.
4. If $AB = 0$ then it does not necessarily mean that $A = 0$ or $B = 0$ or both are 0.
$$\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$
5. $A I_n = I_n A = A$

Example:

if $A = \begin{bmatrix} a & 0 \\ 1 & 1 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 0 \\ 5 & 1 \end{bmatrix}$

then the value of a for which $A^2 = B$ is

A. 1

B. -1

C. 4

D. None of these

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Example: Find the value of $\begin{bmatrix} 4 & 5 & 6 \\ 3 & 2 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} = 0$.

The transpose of a matrix for the matrix A , the matrix obtained by interchanging rows and columns is called Transpose of matrix A and is denoted by A' or A^T .

properties of transpose.

1. $(A')' = A$
2. $k(A') = (kA)'$; k being a scalar.
3. $(A+B)' = A' + B'$
4. $(AB)' = B'A'$
5. $(ABC)' = C'B'A'$

Ex: if matrix A , $A = \begin{bmatrix} a & b & c \\ b & c & a \\ c & a & b \end{bmatrix}$ where a, b, c are

real positive numbers, $abc = 1$ and $A^T A = I$, then find the value of $a^3 + b^3 + c^3$.

- A) 6 B) 2 C) 4 D) 0

Ex: if P is a 3×3 matrix such that $P^T = 2P + I$, where P^T is the transpose of P and I is the 3×3 identity matrix; then there exists a column matrix $X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ such that

- A) $PX = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ B) $PX = X$ C) $PX = 2X$ D) $PX = 0$

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* Trace of matrix *

if $A = [a_{ij}]_{m \times m}$ be a square matrix then the sum of its diagonal elements is defined as the trace of the matrix A and is written as $\text{Tr}(A)$

properties of trace.

1. $\text{Tr}(PA) = P \text{Tr}(A)$
2. $\text{Tr}(PA + QB) = P \text{Tr}(A) + Q \text{Tr}(B)$.
3. $\text{Tr}(AB) = \text{Tr}(BA)$, provided AB and BA

Some special matrices.

1. Symmetric matrix.

Matrix in which $[a_{ij}] = [a_{ji}]$ is called symmetric matrix.

Here, $A' = A$.

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2. Skew symmetric matrix in which $[a_{ij}] = -[a_{ji}]$ is called skew-symmetric matrix.

$$\text{Here, } A' = -A.$$

properties of symmetric and skew-symmetric matrix

1. In skew symmetric matrix all the diagonal elements are zero.

2. For any matrix $(A+A')$ is always symmetric and $(A-A')$ is skew symmetric.

$$B = A + A^T$$

$$B^T = (A + A^T)^T$$

$$B^T = A^T + (A^T)^T$$

$$B^T = A^T + A$$

$$C = A - A^T$$

$$C^T = (A - A^T)^T$$

$$C^T = A^T - A$$

$$C^T = -(A - A^T)$$

3. Any matrix can be written as sum of symmetric and skew symmetric matrix.

$$A = \frac{(A + A^T)}{2} + \frac{(A - A^T)}{2}$$

Ex: Let X and Y be two arbitrary, 3×3 , non-zero, skew symmetric matrices and Z be an arbitrary 3×3 , non-zero, symmetric matrix. Then which

of the following matrices is (are) skew-symmetric?

A. $Y^3 Z^4 - Z^4 Y^3$

B. $X^{44} + Y^{44}$

C. $X^4 Z^3 - Z^3 X^4$

D. $X^{23} + Y^{23}$

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orthogonal matrix :- A square matrix 'A' is said to be orthogonal if $A^T A = A A^T = I$

$$A^T A = A A^T = I$$

Idempotent matrix :- $A^2 = A$

$$A^2 = A$$

Involutory matrix :- A matrix 'A' will be called an involutory matrix if $A^2 = I$ (unit matrix)

$$A^2 = I$$

periodic matrix :- A matrix 'A' will be called a periodic matrix if $A^{k+1} = A$ where k is least positive integer for which $A^{k+1} = A$, then k is said to be the period of A.

$$A^{k+1} = A \text{ where } k \text{ is period of } A$$

Nilpotent matrix :- A matrix 'A' will be called nilpotent matrix if $A^k = 0$ (null matrix), k is least positive integer and k is called index of the nilpotent matrix.

$$A^k = 0, \text{ k is index of } A$$

Ex:- if A, B are two idempotent matrices and $AB = BA = 0$ then $A+B$ is

- A. Involutory matrix B. Idempotent matrix
C. orthogonal matrix D. Nilpotent matrix

$$\text{Ans:- } A^2 = A \quad ; \quad B^2 = B$$

$$(A+B)^2 = (A+B)(A+B)$$

$$= A^2 + AB + BA + B^2$$

$$= A^2 + B^2$$

Ex! - Let A is a matrix of order 2×2 such that $A^2 = 0$. Then $\text{Tr}(A)$ is:

- A) 1 B) 0 C) -1 D) None

Ans:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}; \quad A^2 = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$A^2 = \begin{bmatrix} a^2 + bc & ab + bd \\ ac + cd & bc + d^2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$= b(a+d) = 0 \quad a+d \neq 0 \Rightarrow b = 0 \text{ \& } c = 0.$$

$$c(a+d) = 0 \quad \because a^2 + bc = 0$$

$$\Rightarrow a = 0, \quad bc + d^2 = 0 \Rightarrow d = 0$$

— \therefore DETERMINANTS \therefore —

Determinant

It is a number.

It is defined only for a square matrix.

Determinant of matrix A is written as $|A|$

Minors:

minors of an element $[a_{ij}]$ is expressed as M_{ij} and is obtained by removing i^{th} row and j^{th} column.

Ex! - Find minor M_{23} in the following terms.

$$\begin{bmatrix} 1 & 2 \\ 4 & -1 \end{bmatrix}$$

$$-1 - 8 = -9.$$

$$\begin{vmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 4 & -1 & 2 \end{vmatrix}$$

— : Cofactor : —

Cofactor of an element $[a_{ij}]$ is expressed as c_{ij} and is calculated as

$$c_{ij} = (-1)^{i+j} m_{ij}$$

Ex! - find cofactor c_{23} .

$$m_{23} = \begin{vmatrix} 1 & 2 \\ 4 & -1 \end{vmatrix}$$

$$\begin{vmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 4 & -1 & 2 \end{vmatrix}$$

$$m_{23} = -1 - 8 = -9.$$

$$c_{23} = (-1)^{2+3} m_{23}$$

$$c_{23} = -1 \times -9 = 9$$

Calculation of Determinant

It is the sum of product of elements of a row (or column) with their corresponding cofactors.

$$A = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$$

$$|A| = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$$

$$D = a_{11}c_{11} + a_{12}c_{12} + a_{13}c_{13}$$

Ex! Evaluate the following determinants:

$$\begin{vmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 4 & -1 & 2 \end{vmatrix}$$

Ex!- if $\begin{vmatrix} 6i - 3i & 1 \\ 4 & 3i & -1 \\ 20 & 3 & 1 \end{vmatrix} = x + iy$, then

A. $x=3, y=1$

B. $x=1, y=3$

C. $x=0, y=3$

D. $x=0, y=0$

Multiplication of scalar to a determinant

The scalar (number) gets multiplied in any one row or column.

Ex!- let $P = [a_{ij}]$ be a 3×3 matrix and let $Q = [b_{ij}]$ where $[b_{ij}] = 2^{i+j} [a_{ij}]$ for $1 \leq i, j \leq 3$. If the determinant of P is 2. Then the determinant of the matrix of Q is

A. 2^{10}

B. 2^{11}

C. 2^{12}

D. 2^{13}

$$|P| = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \Rightarrow |Q| = \begin{matrix} i+j \\ 2|P| \\ = \begin{vmatrix} 2^2 a_{11} & 2^3 a_{12} & 2^4 a_{13} \\ 2^3 a_{21} & 2^4 a_{22} & 2^5 a_{23} \\ 2^4 a_{31} & 2^5 a_{32} & 2^6 a_{33} \end{vmatrix} \end{matrix}$$

$$|Q| = (2^2)(2^3)(2^4)(2)(2^2)|P|$$

$$|Q| = 2^{12} \times |P|$$

$$= 2^{12} \times 2$$

$$|Q| = 2^{13}$$

properties of Determinants:—

1. Determinant is zero if any row or column is zero.
2. Determinant is zero if two rows or columns have equal or proportional values.
3. Value of determinant changes by a minus sign if we exchange two rows or two columns.
4. Elementary row or column transformations do not change the value of determinant.

$$R_1 \rightarrow R_1 + R_3 \rightarrow R_3 + mR_2$$

5. $|AB| = |A| |B|$

6. $|A^T| = |A|$

7. $|kA| = k^n |A|$; n is order of A .

Important results.

1. Determinant of skew symmetric matrix of odd order is zero.
2. Determinant of diagonal matrix is equal to the product of its diagonal elements.
3. If a number is multiplied to a determinant, it gets multiplied in any row or column.

Singular and non-singular matrix.
 Matrix whose determinant is zero is called singular matrix otherwise it is non-singular matrix.

Ex:-

$2c$	$2c$	$c-a-b$
$a-b-c$	$2a$	$2a$
$2b$	$b-c-a$	$2b$

- A. $(a+b+c)^2$ B. $(a+b+c)^3$ C. $(a+b+c)$ D. $(a+b+c)^4$

Ex:- The determinant $\begin{vmatrix} a & b & a+b \\ b & c & b+c \\ a+b & b+c & 0 \end{vmatrix}$ is equal to zero if

- A. a, b, c are in AP
 B. a, b, c are in GP
 C. a, b, c are in HP
 D. a is a root of the equation $ax^2 + 2bx + c = 0$

Ex:- if a, b, c are sides of a triangle and

$$\begin{vmatrix} a^2 & b^2 & c^2 \\ (a+1)^2 & (b+1)^2 & (c+1)^2 \\ (a-1)^2 & (b-1)^2 & (c-1)^2 \end{vmatrix} = 0, \text{ then}$$

- A. $\triangle ABC$ is equilateral
 B. $\triangle ABC$ is a isosceles
 C. $\triangle ABC$ is a right angled triangle
 D. $\triangle ABC$ is a scalene triangle.

- : Inverse of a Matrix :-

Let A be any n -rowed square matrix. Then a matrix B , if exists such that $AB = BA = I_n$ is called the inverse of A .

inverse of A is usually denoted by A^{-1} (if exists)

$$A(\text{adj } A) = |A| I$$

$$A \begin{pmatrix} 1 & \text{adj } A \\ |A| \end{pmatrix} = I$$

properties of Inverse matrix

1. Every invertible matrix possess a unique inverse
2. if A and B are invertible matrices of the same order, then AB is invertible and $(AB)^{-1} = B^{-1}A^{-1}$.
3. if A is invertible square matrix, then A^T is also invertible and $(A^T)^{-1} = (A^{-1})^T$
4. $|A^{-1}| = |A|^{-1}$

Ex: if $A = \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{bmatrix}$, find A^{-1}

Ex: $A = \begin{bmatrix} 1 & -1 & 1 \\ 2 & 1 & -3 \\ 1 & 1 & 1 \end{bmatrix}$ and $10B = \begin{bmatrix} 4 & 2 & 2 \\ -5 & 0 & a \\ 1 & -2 & 3 \end{bmatrix}$

if B is inverse of A then a is :-

Inverse using elementary transformations

Ex:- if $A = \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{bmatrix}$, find A^{-1}

Cayley - Hamilton Theorem.

Every square matrix satisfies a specific polynomial equation known as characteristic equation.

$$P(\lambda) = |A - \lambda I|$$

$$P(A) = 0$$

$$a_1 \lambda^3 + b_1 \lambda^2 + c_1 \lambda + d_1 = 0$$

$$a_1 A^3 + b_1 A^2 + c_1 A + d_1 I = 0$$

Ex:- if $A = \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{bmatrix}$, prove that $A^2 - 4A - 5I = 0$

Ex:- $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & -2 & 4 \end{bmatrix}$ and $I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ and

$$A^{-1} = \left[\frac{1}{6} (A^2 + cA + dI) \right]$$

Then the value of c and d are:

A. (-6, -11) . B. (6, 11) . C. (-6, 11) . D. (6, -11)

System of linear simultaneous equations.

$$\begin{aligned} a_1x + b_1y &= c_1 \\ a_2x + b_2y &= c_2 \end{aligned}$$

I. $\frac{a_1}{a_2} \neq \frac{b_1}{b_2}$ Unique Solution

II. $\frac{a_1}{a_2} = \frac{b_1}{b_2} \neq \frac{c_1}{c_2}$ No solution

III. $\frac{a_1}{a_2} = \frac{b_1}{b_2} = \frac{c_1}{c_2}$ Infinite solution.

Ex: The number of values of k for which the system of equations

$(k+1)x + 8y = 4k$; $kx + (k+3)y = 3k-1$ has infinitely many solutions is.

A 0 B 1 C 2 D infinite

Ans:
$$\begin{aligned} (k+1)x + 8y &= 4k \\ kx + (k+3)y &= 3k-1 \end{aligned}$$

$$\frac{k+1}{k} = \frac{8}{k+3} = \frac{4k}{3k-1}$$

to get ans.

$$k = 1 \text{ \& } k = 3.$$

System of linear simultaneous Equations

$$a_1x + b_1y + c_1z = d_1$$

$$a_2x + b_2y + c_2z = d_2$$

$$a_3x + b_3y + c_3z = d_3$$

$$A = \begin{bmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{bmatrix}, \quad X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, \quad B = \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix}$$

$$\Rightarrow AX = B$$

method 1 matrix method

a) $\Delta \neq 0$, then A^{-1} exists

$$\Rightarrow A^{-1}(AX) = A^{-1}B$$

$$\Rightarrow X = A^{-1}B$$

and therefore unique values of x, y and z are obtained.

b) $\Delta = 0$ then A^{-1} does not exist

we have $AX = B$

$$\Rightarrow (\text{adj } A)A X = (\text{adj } A)B$$

$$\Rightarrow \Delta X = (\text{adj } A)B$$

1. $(\text{adj } A)B = 0$, then the system $AX = B$ has infinitely many solutions.

2. $(\text{adj } A)B \neq 0$ then the system $AX = B$ has no solution.

Determinant method of solution

$$a_1x + b_1y + c_1z = d_1$$

$$a_2x + b_2y + c_2z = d_2$$

$$a_3x + b_3y + c_3z = d_3$$

$$A = \begin{bmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{bmatrix}, \quad X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, \quad B = \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix}$$

$$AX = B$$

method 2 (Cramer's Rule)

$$\text{let } |A| = \Delta = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}, \quad \Delta_x = \begin{vmatrix} d_1 & b_1 & c_1 \\ d_2 & b_2 & c_2 \\ d_3 & b_3 & c_3 \end{vmatrix}$$

obtained on replacing first column of Δ by B

$$\text{Similarly, } \Delta_y = \begin{vmatrix} a_1 & d_1 & c_1 \\ a_2 & d_2 & c_2 \\ a_3 & d_3 & c_3 \end{vmatrix} \quad \text{and} \quad \Delta_z = \begin{vmatrix} a_1 & b_1 & d_1 \\ a_2 & b_2 & d_2 \\ a_3 & b_3 & d_3 \end{vmatrix}$$

$$x \cdot \Delta = \Delta_x$$

$$y \cdot \Delta = \Delta_y$$

$$z \cdot \Delta = \Delta_z$$

Case 1

if $\Delta \neq 0$, then the given systems of equations has unique solutions given by

$$x = \frac{\Delta_x}{\Delta}, \quad y = \frac{\Delta_y}{\Delta} \quad \text{and} \quad z = \frac{\Delta_z}{\Delta}$$

Case 2

if $\Delta = 0$, then two sub cases arise :

a) At least one of Δ_x , Δ_y and Δ_z is non-zero

$$x \cdot \Delta = \Delta_x \quad y \cdot \Delta = \Delta_y \quad , \quad z \cdot \Delta = \Delta_z$$

(No solution)

Case 3

if $\Delta = 0$, then two sub cases arise

b) All of Δ_x , Δ_y and Δ_z are zero

Either No solution or Infinite solution

Ex:- Given

$$2x - y + 2z = 2$$

$$x - 2y - z = -4$$

$$x + y + \lambda z = 4$$

then the value of λ , such that the given system of equation has No solution

A. 3 B. 1 C. 0 D. -1

Solution of homogeneous simultaneous equations

$$a_1x + b_1y + c_1z = 0$$

$$a_2x + b_2y + c_2z = 0$$

$$a_3x + b_3y + c_3z = 0$$

$$\Delta = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

$$\Delta_1 = \begin{vmatrix} d_1 & b_1 & c_1 \\ d_2 & b_2 & c_2 \\ d_3 & b_3 & c_3 \end{vmatrix}$$

$$\Delta_y = \begin{vmatrix} a_1 & d_1 & c_1 \\ a_2 & d_2 & c_2 \\ a_3 & d_3 & c_3 \end{vmatrix}$$

$$\Delta_2 = \begin{vmatrix} a_1 & b_1 & d_1 \\ a_2 & b_2 & d_2 \\ a_3 & b_3 & d_3 \end{vmatrix}$$

Ex: The system of equation:

$$\lambda x + y + z = 0$$

$$-x + \lambda y + z = 0$$

$$-x - y + \lambda z = 0$$

will have a non-zero solution if real values of λ are given by:

$$\Delta = \begin{vmatrix} \lambda & 1 & 1 \\ -1 & \lambda & 1 \\ -1 & -1 & \lambda \end{vmatrix} = 0$$

$$\lambda(\lambda^2 + 1) - 1(-\lambda - 1) + 1(1 - \lambda)$$

$$\lambda^3 + \lambda + \lambda + 1 + 1 - \lambda = 0$$

$$\lambda^3 + 3\lambda = 0$$